

Computer Vision

Main problems and mostly used architectures

Main Problems

Classification

Semantic Segmentation

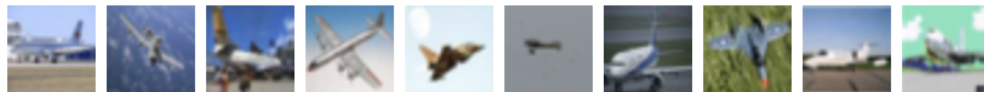
Object Detection, Instance Segmentation

Classification

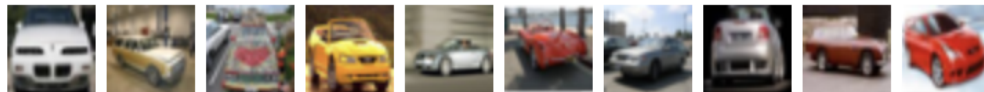
Given an image x , the goal is to classify the image by assigning it to a specific label from the given labels set: y_i

$P(x|\theta) = y_c$ where $c \in \{1\dots n\}$, n is the number of classes

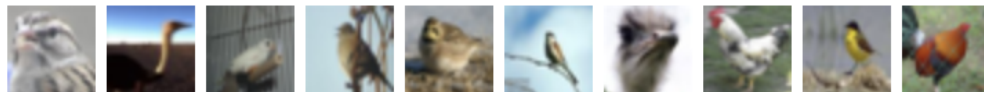
airplane



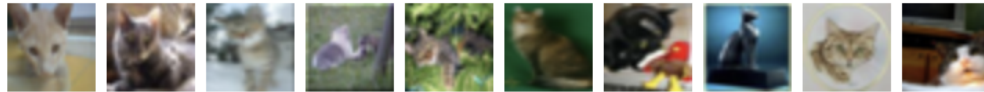
automobile



bird



cat



deer



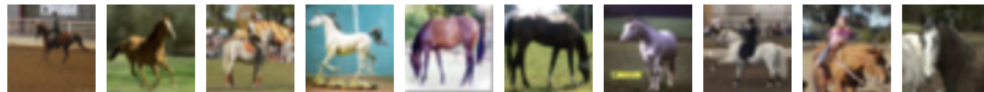
dog



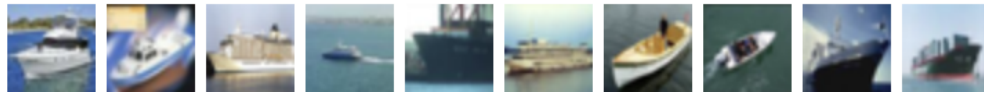
frog



horse



ship



truck



Common Architectures

AlexNet

VGG

ResNet

Inception v3

GoogLeNet

Semantic Segmentation

Given an image x , the goal is to label each pixel of the x with a corresponding class of what is being represented.

$$P(x_{i,j} | \theta) = y_c \text{ where } i, j \in \{H, W\}, c \in \{1 \dots n\},$$

H and W are the x image height and width respectively, n is the number of classes



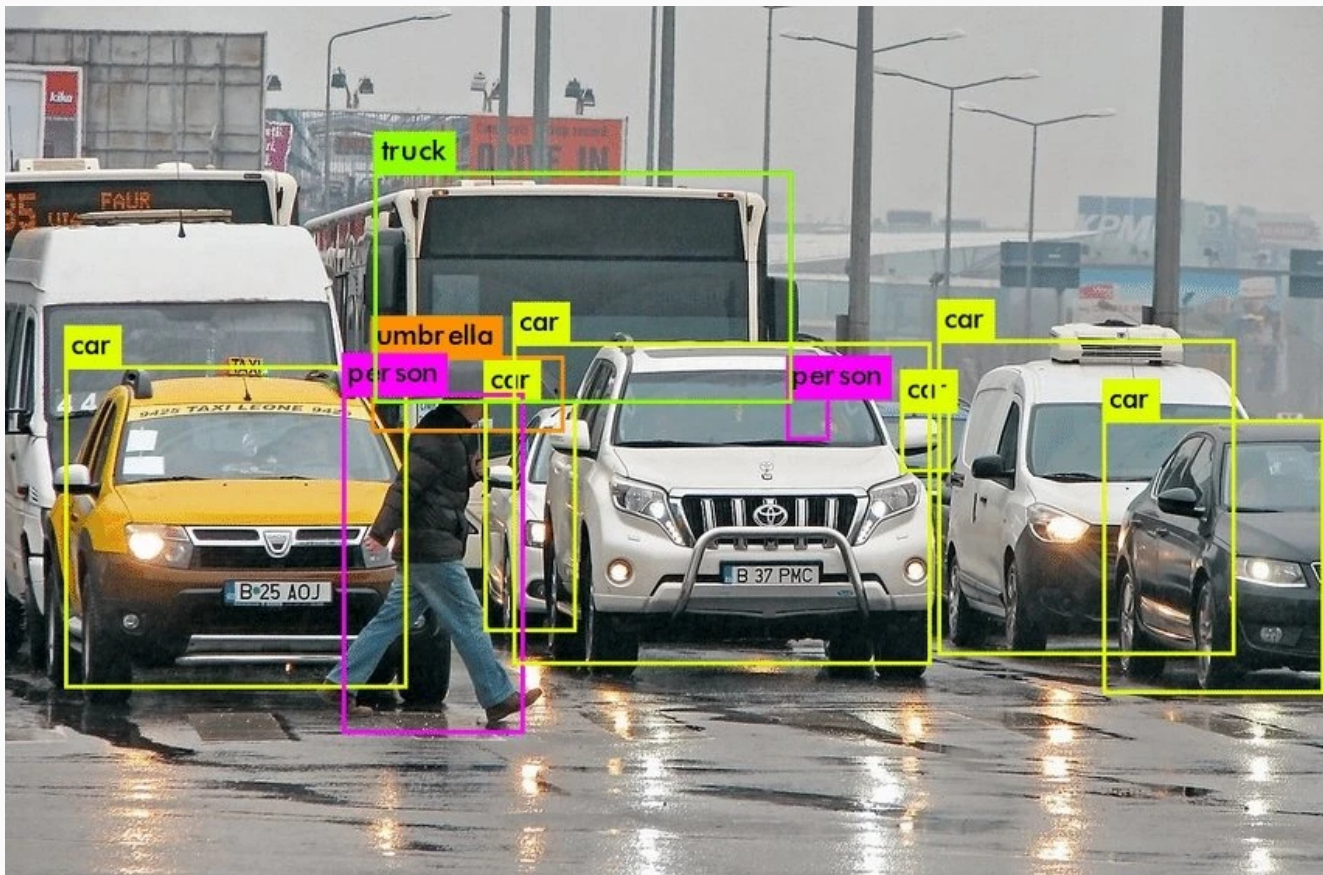
Common Architectures

ResNet

Object Detection, Instance Segmentation

Given an image x , the goal is to identify and locate (draw boundaries) objects in it. Instance segmentation receives the window of an object and applies segmentation.

$$P(x|\theta) = \{z_i\} \text{ where } z_i \in \text{set } Z, z_i = \{(\text{bounding-box, class})\dots\}$$



Common Architectures

R-CNN

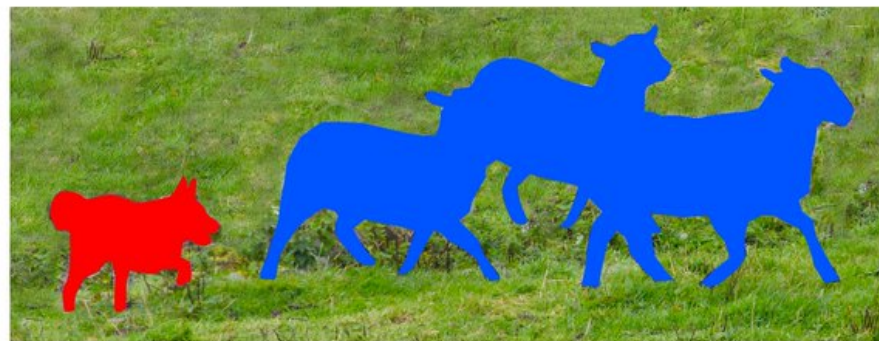
RetinaNet

SSD

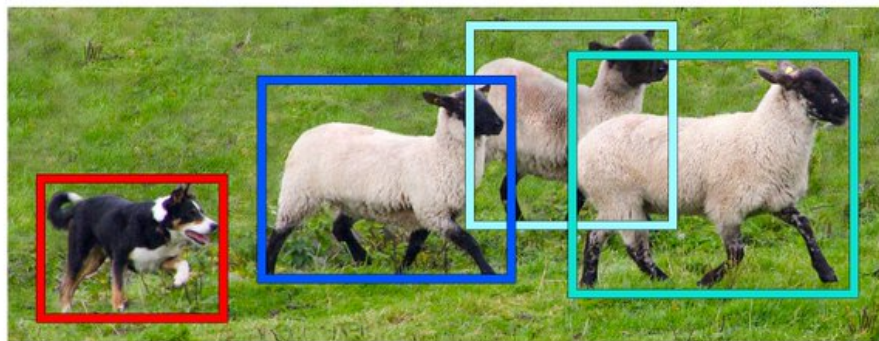
Yolo



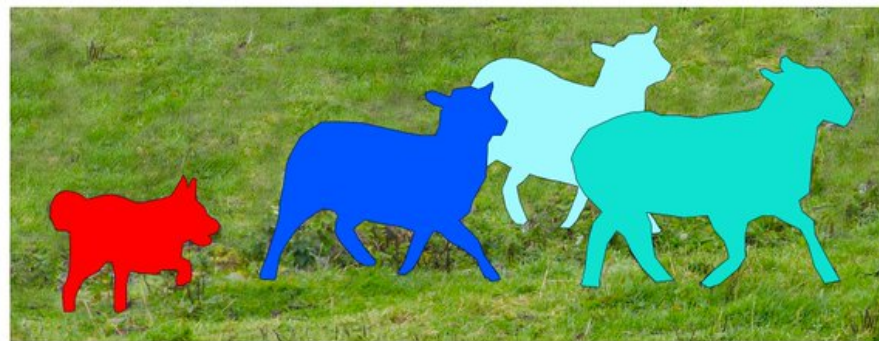
Image Recognition



Semantic Segmentation



Object Detection



Instance Segmentation

Thank You